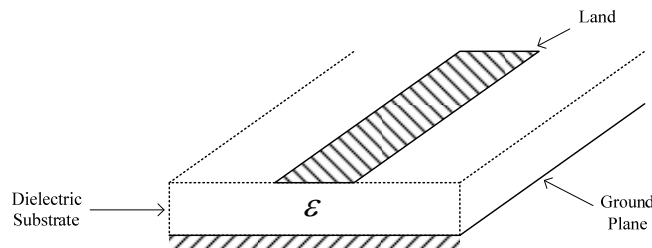


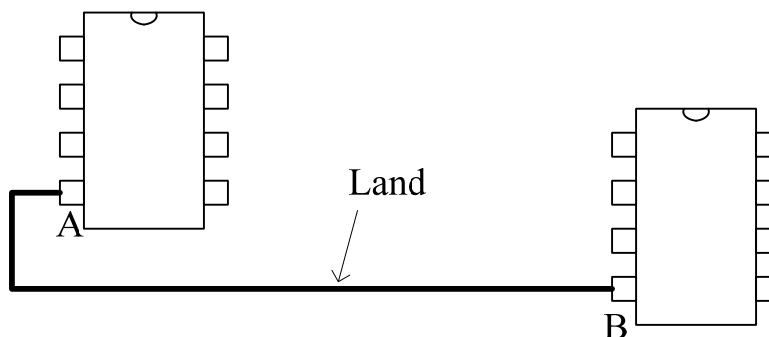
## Lecture 2: Telegrapher Equations For Transmission Lines. Power Flow.

**Microstrip** is one method for making electrical connections in a microwave circuit. It is constructed with a ground plane on one side of a PCB and “lands” on the other:



Microstrip is an example of a **transmission line**, though technically it is only an approximate model for microstrip, as we will see later in this course.

Why TLs? Imagine two ICs are connected together as shown:



When the voltage at A changes state, does that new voltage appear at B instantaneously? No, of course not.

If these two points are separated by a large electrical distance, there will be a **propagation delay** as the change in state (electrical signal) travels to B. Not an instantaneous effect.

In microwave circuits, even distances as small as a few inches may be “far” and the propagation delay for a voltage signal to appear at another IC may be significant.

This propagation of voltage signals is modeled as a “**transmission line**” (TL). We will see that **voltage and current can propagate along a TL as waves**! Fantastic.

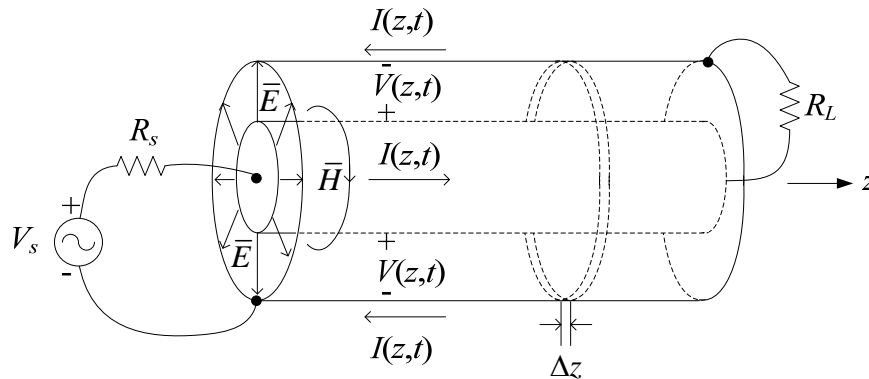
The transmission line model can be used to solve many, many types of high frequency problems, either exactly or approximately:

- Coaxial cable.
- Two-wire.
- Microstrip, stripline, coplanar waveguide, etc.

All true TLs share one common characteristic: the  $\vec{E}$  and  $\vec{H}$  fields are all perpendicular to the direction of propagation, which is the long axis of the geometry. These are called **TEM fields** for transverse electric and magnetic fields.

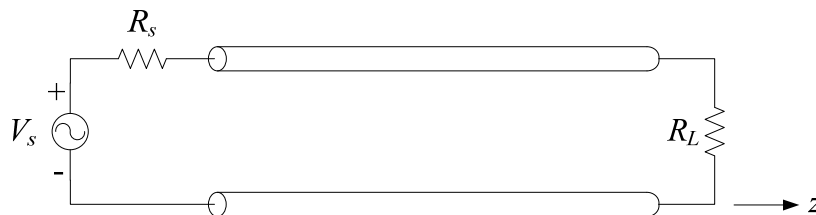
An excellent example of a TL is a coaxial cable. On a TL, the **voltage and current vary along the structure in time  $t$  and**

spatially in the  $z$  direction, as indicated in the figure below. There are no instantaneous effects.



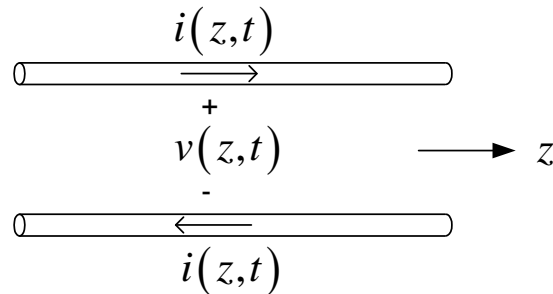
**Fig. 1**

A common **circuit symbol** for a TL is the two-wire (parallel) symbol to indicate any transmission line. For example, the equivalent circuit for the coaxial structure shown above is:



## Analysis of Transmission Lines

As mentioned, on a TL the voltage and current vary along the structure in time ( $t$ ) and in distance ( $z$ ), as indicated in the figure above. **There are no instantaneous effects.**



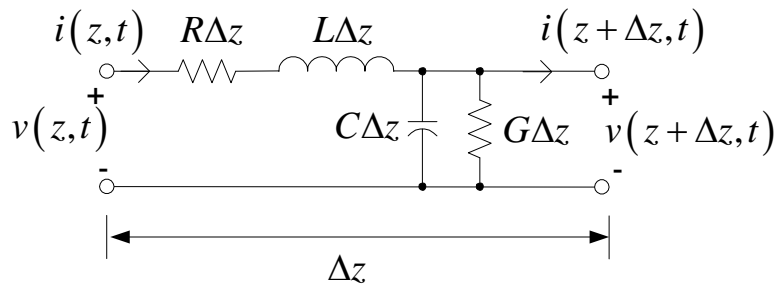
How do we solve for  $v(z,t)$  and  $i(z,t)$ ? We first need to develop the governing equations for the voltage and current, and then solve these equations.

Notice in Fig. 1 above that there is **conduction current** in the center conductor and outer shield of the coaxial cable, and a **displacement current** between these two conductors where the electric field  $\bar{E}$  is varying with time. **Each of these currents has an associated impedance:**

- Conduction current impedance effects:
  - **Resistance**,  $R$ , due to losses in the conductors,
  - **Inductance**,  $L$ , due to the current in the conductors and the magnetic flux linking the current path.
- Displacement current impedance effects:
  - **Conductance**,  $G$ , due to losses in the dielectric between the conductors,
  - **Capacitance**,  $C$ , due to the time varying electric field between the two conductors.

To develop the governing equations for  $V(z,t)$  and  $I(z,t)$ , we will consider only a **small section**  $\Delta z$  of the TL. This  $\Delta z$  is so

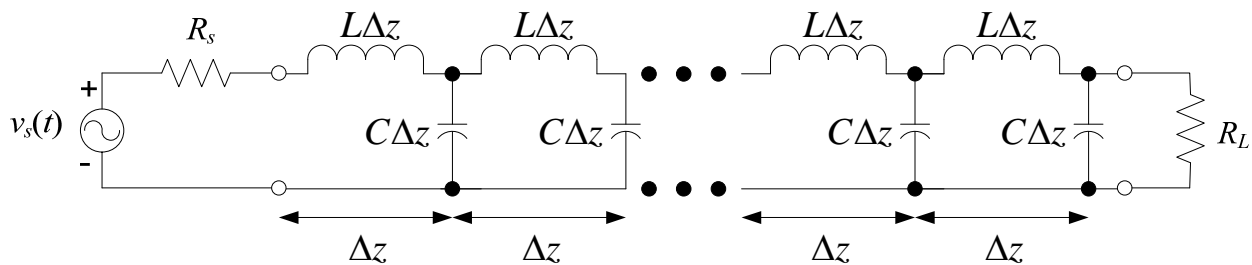
small that the **electrical effects are occurring instantaneously and we can simply use circuit theory** to draw the relationships between the conduction and displacement currents. This equivalent circuit is shown below:



**Fig. 2**

The variables  $R$ ,  $L$ ,  $C$ , and  $G$  are **distributed** (or **per-unit length**, PUL) **parameters** with units of  $\Omega/\text{m}$ ,  $\text{H}/\text{m}$ ,  $\text{F}/\text{m}$ , and  $\text{S}/\text{m}$ , respectively. We will sometimes ignore losses in this course.

A finite length of TL can be constructed by cascading many, many of these subsections along the total length of the TL. In the case of a lossless TL where  $R = G = 0$  this cascade appears as:



This is a **general model**: it applies to **any TL** regardless of its cross sectional shape provided the actual electromagnetic field is TEM.

However, the PUL-parameter values change depending on the **specific geometry** (whether it is a microstrip, stripline, two-wire, coax, or other geometry) and the construction materials.

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## Transmission Line Equations

To develop the governing equation for  $v(z,t)$ , apply KVL in Fig. 2 above (ignoring losses)

$$v(z,t) = L\Delta z \frac{\partial i(z,t)}{\partial t} + v(z + \Delta z, t) \quad (2.1a),(1)$$

Similarly, for the current  $i(z,t)$  apply KCL at the node

$$i(z,t) = C\Delta z \frac{\partial v(z + \Delta z, t)}{\partial t} + i(z + \Delta z, t) \quad (2.1b),(2)$$

Then:

1. Divide (1) by  $\Delta z$ :

$$\frac{v(z + \Delta z, t) - v(z, t)}{\Delta z} = -L \frac{\partial i(z, t)}{\partial t} \quad (3)$$

In the limit as  $\Delta z \rightarrow 0$ , the term on the LHS in (3) is the **forward difference definition** of derivative. Hence,

$$\boxed{\frac{\partial v(z, t)}{\partial z} = -L \frac{\partial i(z, t)}{\partial t}} \quad (2.2a),(4)$$

2. Divide (2) by  $\Delta z$ :

$$\frac{i(z + \Delta z, t) - i(z, t)}{\Delta z} = -C \frac{\partial v(z + \Delta z, t)}{\partial t} \quad (5)$$

Again, in the limit as  $\Delta z \rightarrow 0$  the term on the LHS is the forward difference definition of derivative. Hence,

$$\boxed{\frac{\partial i(z, t)}{\partial z} = -C \frac{\partial v(z, t)}{\partial t}} \quad (2.2b), (6)$$

Equations (4) and (6) are a pair of coupled first order partial differential equations (PDEs) for  $v(z, t)$  and  $i(z, t)$ . These two equations are called the **telegrapher equations** or the **transmission line equations**.

**Recap:** We expect that  $v$  and  $i$  are not constant along microwave circuit interconnects. Rather, (4) and (6) dictate how  $v$  and  $i$  vary along the TL at all times.

## TL Wave Equations

We will now combine (4) and (6) in a special way to form two equations, each a function of  $v$  or  $i$  only.

To do this, take  $\frac{\partial}{\partial z}$  of (4) and  $\frac{\partial}{\partial t}$  of (6):

- $\frac{\partial}{\partial z}$ (4): 
$$\frac{\partial^2 v(z, t)}{\partial z^2} = -L \frac{\partial^2 i(z, t)}{\partial z \partial t} \quad (7)$$

$$\bullet \frac{\partial}{\partial t}(6): \quad \frac{\partial^2 i(z,t)}{\partial t \partial z} = -C \frac{\partial^2 v(z,t)}{\partial t^2} \quad (8)$$

Substituting (8) into (7) gives:

$$\frac{\partial^2 v(z,t)}{\partial z^2} = LC \frac{\partial^2 v(z,t)}{\partial t^2} \quad (9)$$

Similarly,

$$\frac{\partial^2 i(z,t)}{\partial z^2} = LC \frac{\partial^2 i(z,t)}{\partial t^2} \quad (10)$$

Equations (9) and (10) are the governing equations for the  $z$  and  $t$  dependence of  $v$  and  $i$ . These are very special equations. In fact, they are **wave equations** for  $v$  and  $i$ !

We will define the **(phase) velocity** of these waveforms as

$$v_p = \frac{1}{\sqrt{LC}} \quad [\text{m/s}] \quad (2.16)$$

so that (9) becomes

$$\frac{\partial^2 v(z,t)}{\partial z^2} = \frac{1}{v_p^2} \frac{\partial^2 v(z,t)}{\partial t^2} \quad (11)$$

## Voltage Wave Equation Solutions

There are two **general solutions** to (11):

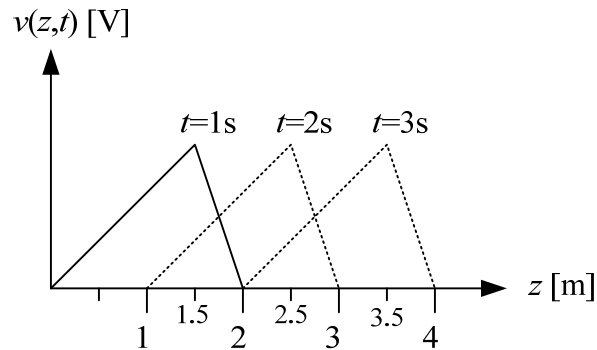
$$\mathbf{1.} \quad v(z,t) = v_+ \left( t - \frac{z}{v_p} \right) \quad (12)$$



$v_+$  is any twice-differentiable function that contains  $t$ ,  $z$ , and  $v_p$  in the form of the argument shown. It can be verified that (12) is a solution to (11) by substituting (12) into (11) and showing that the LHS equals the RHS.

Equation (12) represents a wave traveling in the  $+z$  direction with **speed**  $v_p = 1/\sqrt{LC}$  m/s.

To see this, consider the example below with  $v_p = 1$  m/s:



At  $t = 1$  s, focus on the peak located at  $z = 1.5$  m. Then,

$$s_+ \equiv t - \frac{z}{v_p} = 1 - \frac{1.5}{1} = -0.5$$

The argument  $s_+$  stays **constant** for varying  $t$  and  $z$ . Therefore, at  $t = 2$  s, for example, then

$$s_+ = -0.5 = t - \frac{z}{v_p}$$

Therefore,

$$z = 2.5 \text{ m}$$

So the peak has now moved to position  $z = 2.5$  m at  $t = 2$  s.

Likewise, every point on this function moves the same distance (1 m) in this time (1 s). This is called **wave motion**.

The speed of this movement is

$$\frac{\Delta z}{\Delta t} = \frac{1 \text{ m}}{1 \text{ s}} = 1 \frac{\text{m}}{\text{s}} = v_p$$

$$2. v(z, t) = v_- \left( t + \frac{z}{v_p} \right) \quad (13)$$

This is the second general solution to (11). This function  $v_-$  represents a wave moving in the  $-z$  direction with speed  $v_p$ .

The complete solution to the wave equation (11) is the sum of (12) and (13)

$$v(z, t) = v_+ \left( t - \frac{z}{v_p} \right) + v_- \left( t + \frac{z}{v_p} \right) \quad (14)$$

$v_+$  and  $v_-$  can be any suitably differentiable functions, but with arguments as shown.

## Current Wave Equation Solutions

A similar analysis can be performed for current waves on the TL. The governing equation for  $i(z, t)$  is

$$\frac{\partial^2 i(z, t)}{\partial z^2} = \frac{1}{v_p^2} \frac{\partial^2 i(z, t)}{\partial t^2} \quad (15)$$

The complete general solution to this **current wave equation** can be determined in a manner similar to the voltage as

$$i(z, t) = \underbrace{i_+ \left( t - \frac{z}{v_p} \right)}_{+z \text{ wave}} + \underbrace{i_- \left( t + \frac{z}{v_p} \right)}_{-z \text{ wave}} \quad (16)$$

Furthermore, the function  $i_+$  can be **related** to the function  $v_+$  and  $i_-$  can be related to  $v_-$ .

For example, substituting  $i_+ \left( t - \frac{z}{v_p} \right)$  and  $v_+ \left( t - \frac{z}{v_p} \right)$  into (6), differentiating then integrating gives

$$-\frac{1}{v_p} i_+ = -C v_+$$

or

$$i_+ = v_p C v_+ \quad (17)$$

But,

$$v_p C = \frac{1}{\sqrt{LC}} C = \sqrt{\frac{C}{L}}$$

We will define

$$Z_0 \equiv \sqrt{\frac{L}{C}} \quad [\Omega] \quad (2.13), (18)$$

as the **characteristic impedance** of the transmission line. (Note that in some texts,  $Z_0$  is denoted as  $R_c$ , the characteristic resistance of the TL).

With (18), (17) can be written as

$$i_+ \left( t - \frac{z}{v_p} \right) = \frac{v_+ \left( t - \frac{z}{v_p} \right)}{Z_0} \quad (19)$$

Similarly, it can be shown that

$$i_- \left( t + \frac{z}{v_p} \right) = -\frac{v_- \left( t + \frac{z}{v_p} \right)}{Z_0} \quad (20)$$

The minus sign results since the current is in the  $-z$  direction.

Finally, substituting (19) and (20) into (16) gives

$$i(z, t) = \frac{1}{Z_0} v_+ \left( t - \frac{z}{v_p} \right) - \frac{1}{Z_0} v_- \left( t + \frac{z}{v_p} \right) \quad (21)$$

This equation as well as (14)

$$v(z, t) = v_+ \left( t - \frac{z}{v_p} \right) + v_- \left( t + \frac{z}{v_p} \right) \quad (22)$$

are the **general wave solutions** for  $v$  and  $i$  on a transmission line.

## Power Flow

These voltage and current waves transport power along the TL.

The **power flow** carried by the forward wave  $p_+(z, t)$  is

$$p_+(z, t) = v_+(z, t) i_+(z, t) = \frac{v_+^2(z, t)}{Z_0} \quad (23)$$

which is positive indicating power flows in the  $+z$  direction.

Similarly, the power flow of the reverse wave is

$$p_-(z,t) = v_-(z,t)i_-(z,t) = -\frac{v_-^2(z,t)}{Z_0} \quad (24)$$

which is negative indicating power flows in the  $-z$  direction.